

CLAIMS

- 1 1. A system for reducing a size of an image, comprising:
2 a system for rotating the image in a first direction using a rotation algorithm to
3 generate an intermediate reduced image;
4 a system for rotating the intermediate reduced image in a direction opposite the
5 first direction using the rotation algorithm to generate a final reduced image; and
6 wherein the rotation algorithm uses weighted sums of neighboring pixels in the
7 image prior to rotation to calculate new pixel values.
- 1 2. The system of claim 1, wherein the rotation algorithm calculates each new pixel value
2 using the formula:
3
$$V_o = K_h * K_v (V1 + V4 - V2 - V3) + K_h (V3 - V4) + K_v (V2 - V4) + V4,$$

4 wherein, V_o comprises a rotated data point; V1, V2, V3 and V4 comprise neighboring
5 data points in the image prior to rotation; and K_h and K_v comprise constant values
6 calculated as a function of pixel locations of the rotated image.
- 1 3. The system of claim 2, wherein K_h and K_v are stored in a table.
- 1 4. The system of claim 1, wherein an amount of size reduction is proportional to an
2 amount of rotation implemented by the rotation algorithm.
- 1 5. The system of claim 1, further comprising an enhancement system to boost a dynamic
2 range of the image after the second reduction.

1 7. A program product stored on a recordable medium for reducing a size of an original
2 image, comprising:

3 means for rotating the original image in a first direction to generate an
4 intermediate reduced image;

5 means for rotating the reduced image in a direction opposite the first direction to
6 generate a final reduced image; and

7 wherein the means for rotating the original and intermediate reduced image use
8 weighted sums of neighboring pixels in the image prior to rotation to calculate new pixel
9 values.

1 8. The program product of claim 7, wherein the means for rotating the original and
2 reduced image uses the formula:

$$V_o = K_h * K_v (V1 + V4 - V2 - V3) + K_h (V3 - V4) + K_v (V2 - V4) + V4,$$

3 wherein, V_o comprises a new pixel; $V1$, $V2$, $V3$ and $V4$ comprise neighboring pixels in
4 the image prior to rotation; and K_h and K_v comprise constant values calculated as a
5 function of a pixel locations of the rotated image.
6

1 9. The program product of claim 8, wherein K_h and K_v are stored in a table

1 10. The program product of claim 7, wherein an amount of size reduction is proportional
2 to an amount of rotation.

1 11. The program product of claim 7, further comprising enhancement means to boost a
2 dynamic range of the final reduced image.

1 12. A method of reducing a size of an image, comprising:
 2 providing an original image having W1 pixels in each row;
 3 generating an intermediate reduced image having W2 pixels in each row, wherein
 4 W2 is less than W1, and wherein for each pixel 1 to W2 in each row, pixel values are
 5 calculated based on weighted sums of neighboring pixels in the original image; and
 6 generating a further reduced image having W3 pixels in each row, wherein W3 is
 7 less than W2, and wherein for each pixel 1 to W3 in each row, pixel values are calculated
 8 based on weighted sums of neighboring pixels in the intermediate reduced image.

1 13. The method of claim 12, further comprising:
 2 enhancing the further reduced image to boost a dynamic range of the further
 3 reduced image.

1 14. The method of claim 12, wherein the step of calculating pixel values based on
 2 weighted sums of neighboring pixels in the original image utilizes the formula:
 3
$$W2_o = K_h * K_v (V1 + V4 - V2 - V3) + K_h (V3 - V4) + K_v (V2 - V4) + V4,$$

 4 wherein, W2_o comprises a calculated pixel; V1, V2, V3 and V4 comprise neighboring
 5 pixels in the original image; and K_h and K_v comprise constant values calculated as a
 6 function of the number of pixels W2.

1 15. The method of claim 14, wherein the constant values K_h and K_v are further calculated
 2 as a function of the location of W2_o in a row of pixels W2.

1 17. A system for reducing a size of an original image, wherein the original image has a
2 predetermined number of pixels W1 in a row, the system comprising:

3 a system for generating an intermediate reduced image having a reduced number
4 of pixels W2 in the row, wherein W2 is less than W1, and wherein for each pixel 1 to W2
5 in the row, pixel values are calculated based on weighted sums of neighboring pixels in
6 the original image; and

7 a system for generating a further reduced image having a reduced number of
8 pixels W3 in the row, wherein W3 is less than W2, and wherein for each pixel 1 to W3 in
9 the row, pixel values are calculated based on weighted sums of neighboring pixels in the
10 intermediate reduced image.

1 18. The system of claim 17, further comprising:

2 an enhancement system to boost a dynamic range of the further reduced image.

1 19. The system of claim 17, wherein the pixel values are calculated with the formula:

2
$$W2_o = K_h * K_v (V1 + V4 - V2 - V3) + K_h (V3 - V4) + K_v (V2 - V4) + V4,$$

3 wherein, W2_o comprises a calculated pixel; V1, V2, V3 and V4 comprise neighboring
4 pixels in the original image; and K_h and K_v comprise constant values calculated as a
5 function of the number of pixels W1.

1 20. The system of claim 19, wherein the constant values K_h and K_v are further calculated
2 as a function of the location of W2_o in the row of W2 pixels.

